

OSAL REFERENCE

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1 OPERATING SYSTEM ABSTRACTION LAYER(OSAL)

OSAL is a glue layer between the Smart Access library and the customers underlying operating system. It needs to support the customers CAN, RS485 and Ethernet drivers. The OSAL implementation should provide the following functionality:

1.1 OSAL INTERFACE

In this section is provided a platform independent interface description, which can be commonly implemented for Linux, Windows or other operating systems.

1.1.1 GETTING OSAL INSTANCE

The upper layer(Smart Access Library) shall be able to retrieve the OSAL instance by calling the function below:

```
static std::shared_ptr<OSALIface> GetOSAL();
```

It could be implemented in the following way:

```
static std::shared_ptr<OSALImpD instance;

std::shared_ptr<OSALIface> OSALIface::GetOSAL()
{
    if (!instance)
    {
        instance.reset(new OSALImpl());
    }
    return instance;
}
```

1.1.2 INITIALIZATION

The upper layer(Smart Access Library) shall be able to initialize the OSAL layer:

```
virtual bool Init(IN const std::string& configPath) = 0;
```

Returns true, if the initialization was successful and false, if it failed. It gets a configuration path (please see configuration section of this manual) as argument.

1.1.3 GETTING LIST OF HW DEVICES

The upper layer(Smart Access Library) shall be able to retrieve from OSAL a list of all supported hardware devices:

Where **HwlfaceDescriptor** is the base class, those descendants are:

1.1.3.1 HW CAN DESCRIPTOR Class HwCanDescriptor has the following members:



```
private:
    CanDevId    __deviceId;
    std::string    __ifaceName;
    uint32_t    __baudrate;
```

- _deviceId CAN device id. IMPORTANT: it must match with device id from the routing table.
- _ifaceName CAN interface name.
- _baudrate CAN baudrate .

For more information please see ExternalTypes.h file.

1.1.3.2 HW RS485 DESCRIPTOR Class HwRS485Descriptor has the following members:

- _deviceId Serial Device Id. IMPORTANT: it must match with device id from the routing table.
- _ifaceName Interface name e.g. "/dev/ttyS0" or "COM1".
- _baudrate
 RS485 baudrate.

For more information please see ExternalTypes.h file.

1.1.3.3 HW ETHERNET DESCRIPTOR Class HwEthernetDescriptor has the following members:

```
private:
    uint16_t    _deviceId;
    std::string    _ifaceName;
    std::string    _ip;
    uint32_t    _port;
```

- _deviceId
 Ethernet adapter device id.
- _ifaceName Interface name e.g. "eth0".
- _ip IP Address.
- _port UDP port.

For more information please see ExternalTypes.h file.

1.1.4 HW REGISTRY

The purpose of Hardware Registries is to describe a certain physical interface. As opposed to a hardware descriptor it describes both real physical hardware devices e.g. CAN and logical ones e.g. UDP sockets. **HwRegistry**, similar to **HwlfaceDescriptor**, is used in the interface as a base class and needs to be casted in OSAL implementation to its descendants:

1.1.4.1 CAN HW REGISTRY Class CanHwRegistry has the following members:

- _ids - List of CAN Identifiers that shall be received by CAN device, the rest needs to be dropped.



- _ deviceId - CAN device ID. The same id as in the hardware descriptor.

For more information please see ExternalTypes.h file.

1.1.4.2 RS485 HW REGISTRY Class Rs485HwRegistry has the following members:

```
private:
SerialDevId __deviceId
```

- _deviceId - Serial device ID. The same ID as in the hardware descriptor.

For more information please see ExternalTypes.h file.

1.1.4.3 ETHERNET HW REGISTRY Class EthernetRegistry has the following members:

```
        private:
        std::string
        _ip;

        uint32_t
        _port;

        EthTransportType
        _transType;
```

```
_ip - IP address.
```

- _port UDP/TCP port.
- _ transType Transport type TCP/UDP/UDP MULTICAST (TCP is currently not supported).

For more information please see ExternalTypes.h file.

1.1.5 REGISTER RECEIVER

In order to receive incoming packets, the upper layer need to be able to register receiver callbacks, these callbacks shall be invoked upon receiving data on the described in hardware registry interface.

The receiver callback has the following format:

```
typedef std::function<void(BufferDescriptor&)> ReceiverCallback;
```

Where the buffer descriptor is built as follows:

```
class BufferDescriptor
{
public:
    BufferDescriptor(uint8_t* bufferPtr, size_t size);
    BufferDescriptor();

~BufferDescriptor();

uint8_t* GetBufferPtr() const;
size_t GetSize() const;
void SetBufferPtr(IN uint8_t* bufferPtr);
void SetSize(IN size_t size);

private:
    uint8_t* __bufferPtr;
    size_t __bufferPtr;
    size_t __size;
```



};

- _bufferPtr Pointer to the allocated buffer. Please notice that the OSAL is responsible to allocate and to free this memory.
- _size Size of the allocated buffer.

1.1.6 UNREGISTER RECEIVER

In order to remove a previously registered callback, the interface below will be called.

```
virtual ErrorCode UnRegisterReceiver(IN const HwRegistry& registry) = 0;
```

1.1.7 SEND DATA

The upper layer(Smart Access Library) shall be able to send data to a certain hardware registry.

Please do not free this memory it will be freed by the upper layer.

For more information about OSAL interface please see the OSALIface.h file.

1.2 CONFIGURATION

The Osal implementation is configured by the "hw_inventory". The configurations are described in the subsection Linux 1.2.1 and Windows 1.2.2.

1.2.1 Linux

Exemplary CAN configruation:

- type Device type, set to "can".
- dev_id ID of the CAN device required by the OSAL layer for identifying the adapter to be used.
- iface_name Interface name of the used can socket.
- baudrate CAN bus baudrate

Exemplary RS485 configuration:



- type Device type, set to "rs485".
- dev_id ID of the CAN device required by the OSAL layer for identifying the adapter to be used.
- iface_name Interface name of the used rs485 socket.
- baudrate Uart baudrate.

Exemplary Ethernet configuration:

- type Device type, set to "eth".
- dev_id ID of the CAN device required by the OSAL layer for identifying the adapter to be used.
- iface_name Interface name of the used ethernet socket.
- port Receive udp port.

1.2.2 Windows

There is no configuration for an CAN device, because the reference OSAL does not support CAN on Windows.

Exemplary RS485 configuration:

- type Device type, set to "rs485".
- deviceId ID of the CAN device required by the OSAL layer for identifying the adapter to be used.
- usedPort It is the name of the COM port.
- linkSpeed Uart baudrate.

Exemplary Ethernet configuration:

```
"clients" :
```

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```
{
    "type" : "eth",
    "deviceId" : "1",
    "usedPort" : "65000",
    "ipAddress" : "192.168.11.1"
},
......
```

- type Device type, set to "eth".
- deviceId ID of the CAN device required by the OSAL layer for identifying the adapter to be used.
- usedPort Receive udp port.
- ipAddress Used pc ip address.



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